

Make your robot see. A survey on visual navigation technology

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Centrum Badań Kosmicznych PAN (Space Research Centre PAS)

July 08, 2022

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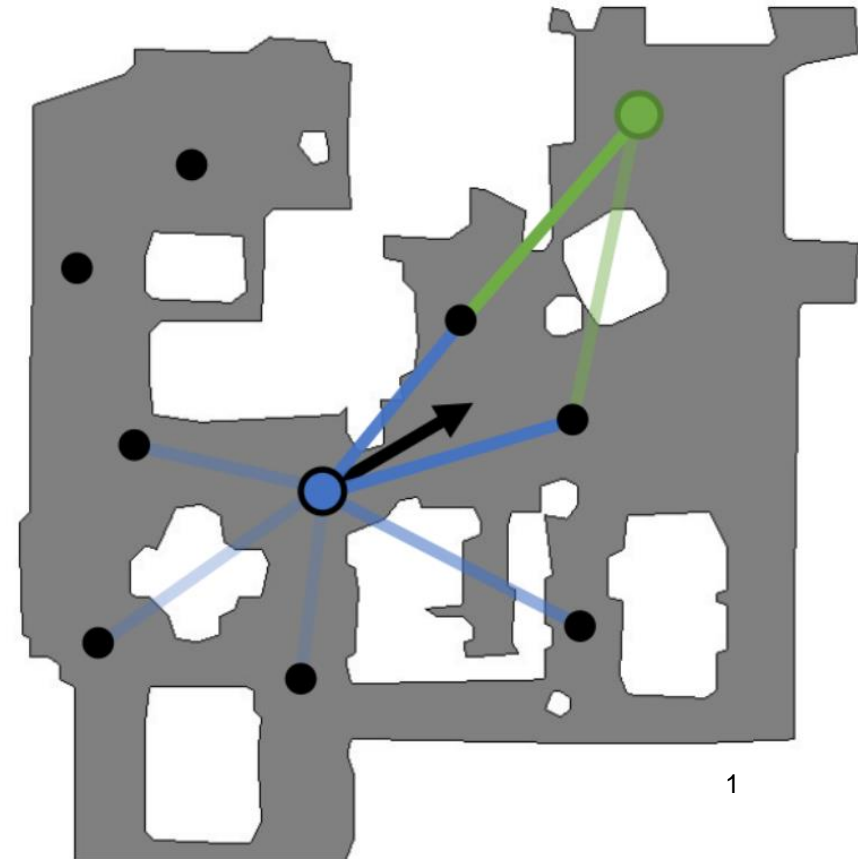
Outline

- Why?
- What's inside?
- What next?

goal image



current observation



1

Why?

- Motivations
 - Cooperation with companies
 - Support the local University
 - Find a new direction



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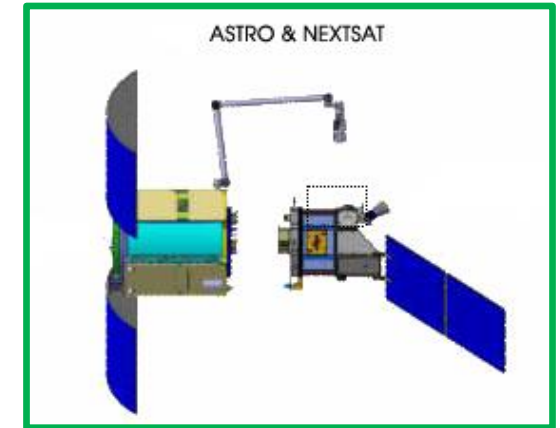
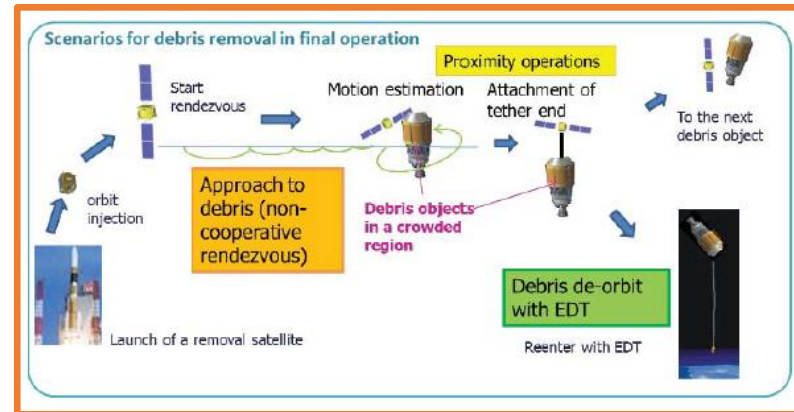
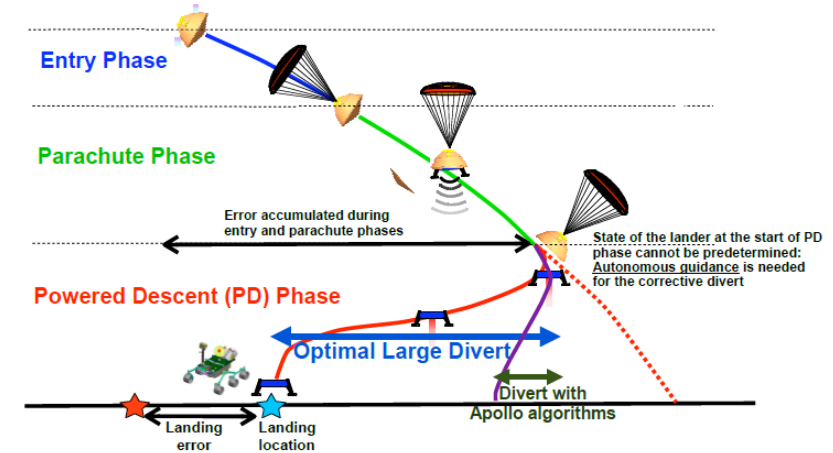
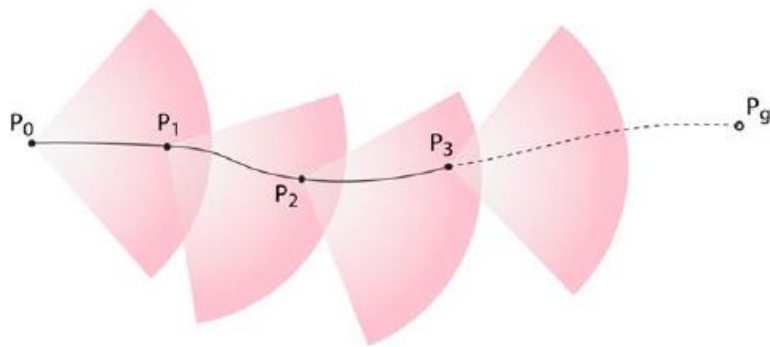
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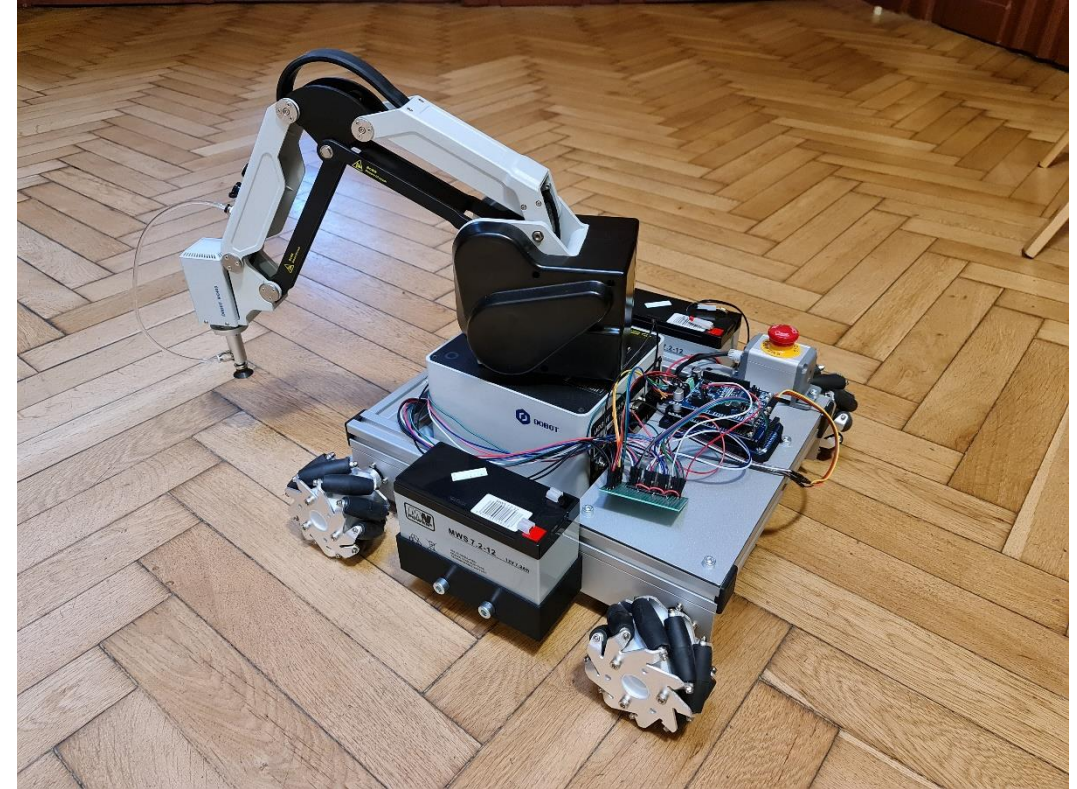
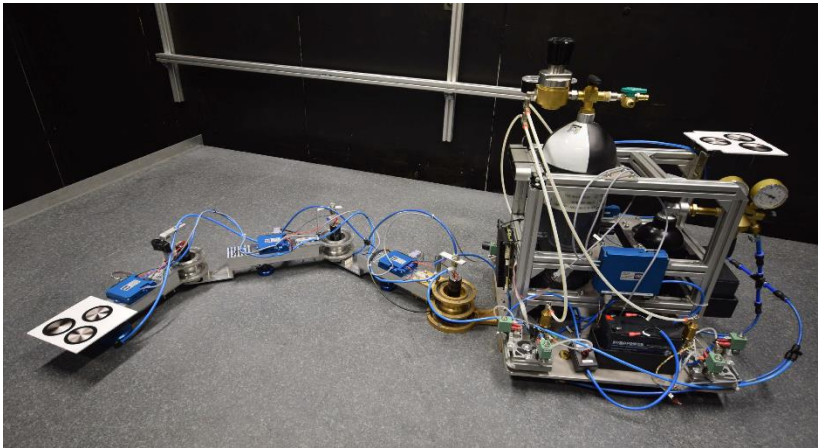
Space application

- RDL (rendez vous, descent, landing)
- OOS (on-orbit servicing)
- ADR (active debris removal)
- FF (formation flying)
- PVN (planetary vehicle navigation)



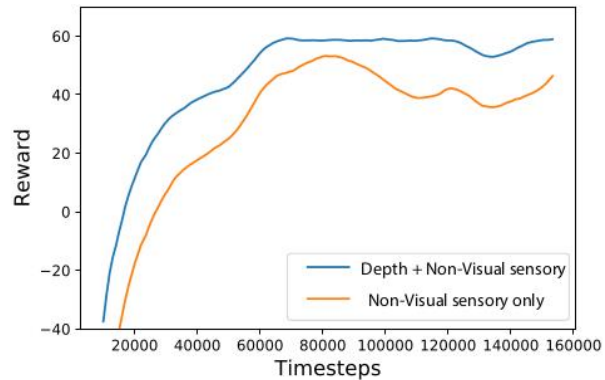
Space applications

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- **ADR (active debris removal)**
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“Regular” applications

- Every autonomously moving object
 - Vacuum cleaner \leftrightarrow car
- Hazardous environment guide



4



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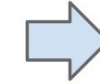
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What's inside?

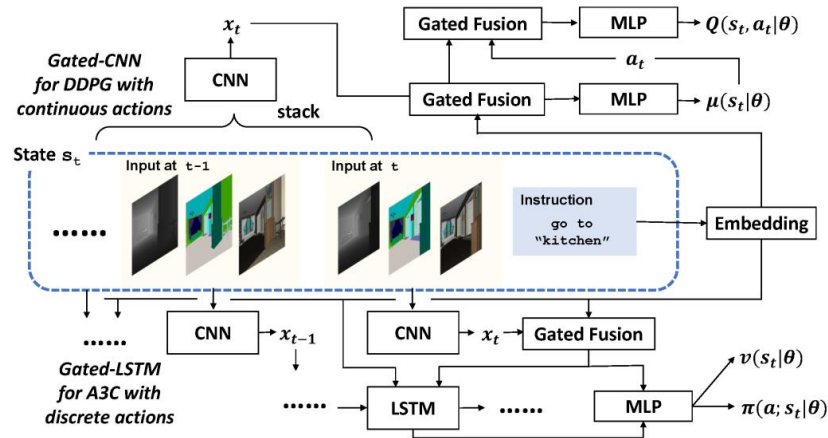
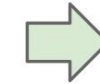
- Visual navigation algorithms
- Learning environments/scene databases
- Hardware
 - Cameras
 - Calculation units



push

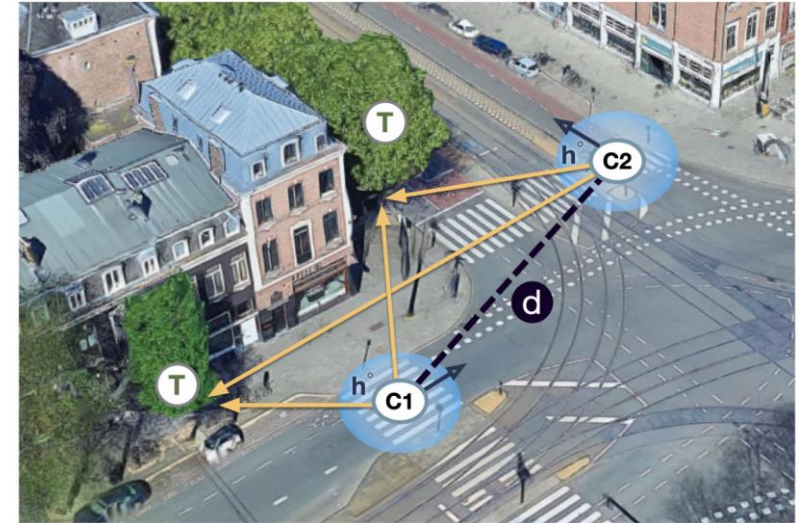


open



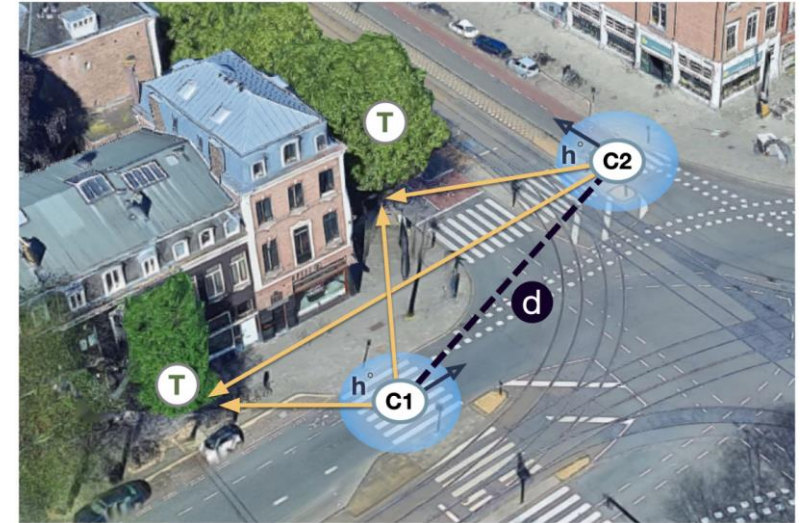
Visual navigation algorithms

- Presentation of the latest and the most effective algorithms:
 - Exploration algorithms
 - Obstacle detection algorithms
 - Comparison of performance
- Based on the articles published in 2020 – 2022
 - Mostly algorithms, which are supported with a github repository



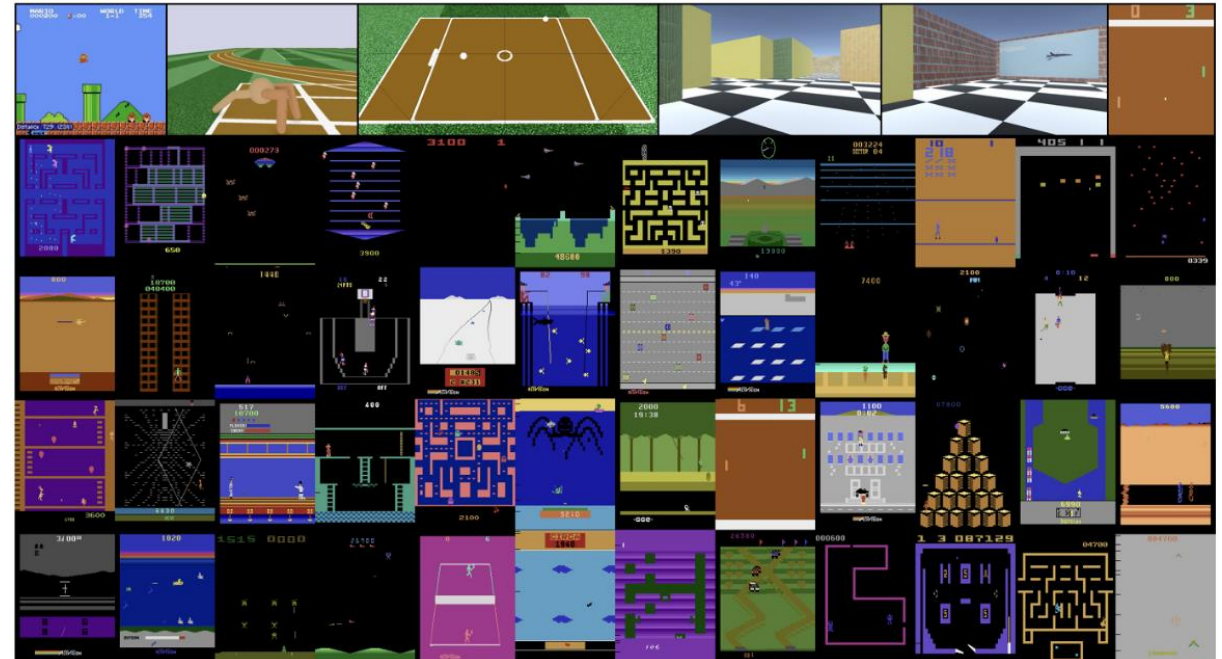
Visual navigation algorithms

- Presentation of the latest and the most effective algorithms:
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- Based on the articles published in 2020 – 2022
 - Mostly algorithms, which are supported with a github repository
 - Problem with the comparison



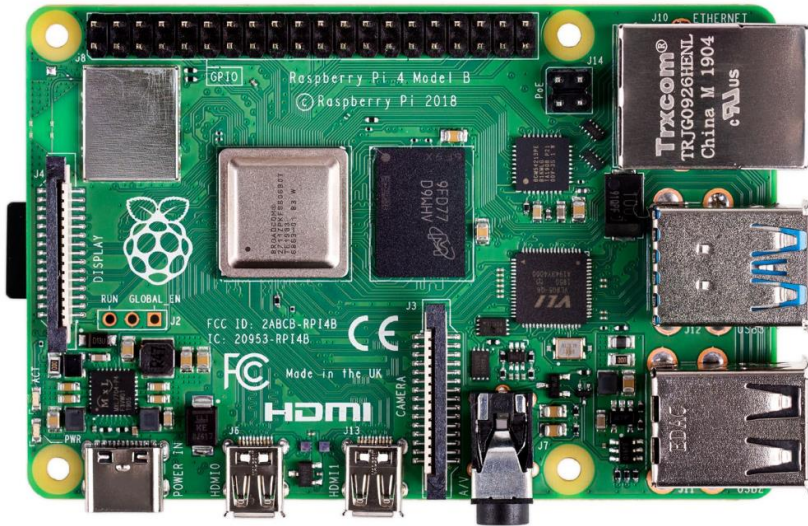
Learning environments

- The latest or the most widespread environments
- Section including quality and application
 - Virtual and real images
 - Indoor and outdoor
 - Simple and realistic texture
- The biggest section
 - Useful for developers
 - Performance comparison



Hardware

- Description of visual hardware and supporting sensors
- Short overview of single-board computers
- Overview of stereo camera sets with parameters
 - Description of software and compatibility



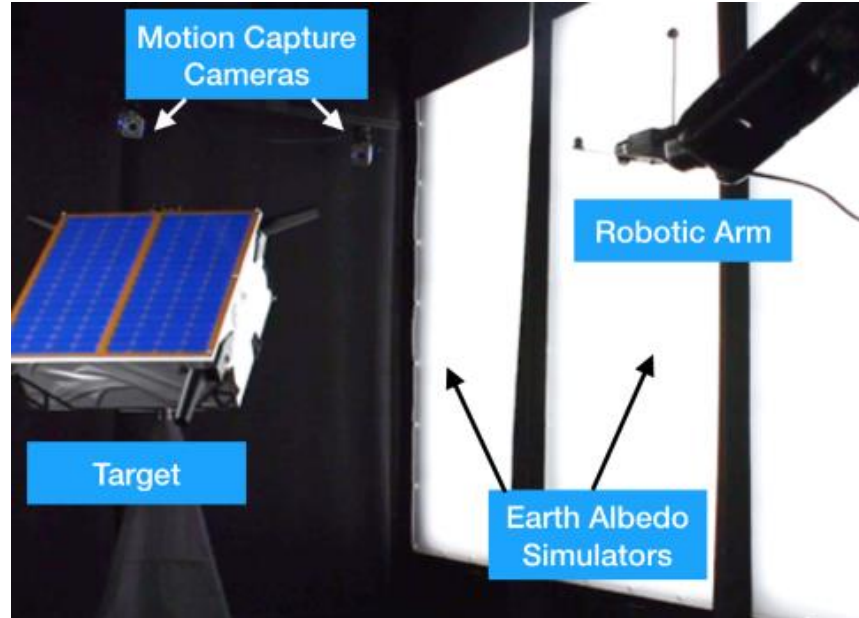
Benefits

- Companies
 - Free knowledge
 - Lower investment risks
 - Cost reduction
- University
 - New students
- Region
 - Innovation indicator



New direction

- Building vision system
 - Rover
 - Manipulator
- Creating a scene database for space applications
- New way of algorithms testing



Conclusions

- Free, organized knowledge
- Money saving
- Attract investors
- New project
- Innovation indicators





SpaceRegion



Thank you

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"Barrieren reduzieren - gemeinsame Stärken nutzen" / „Redukować bariery – wspólnie wykorzystywać silne strony”

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